Basic Things Required for Line Follow Robot

1. DIY chassis for the body
2. 20 - 25 jumper cables (male to male)
3. 10 – 15 jumper cables (male to female)
4. 2 motors
5. Arduino Genuino Uno Microcontroller
6. Breadboard
7. 3 Infra-Red Sensors
8. 2 large rubber wheels to be attached to the motor
9. One smaller ball bearing wheel to be attached in the front of the chassis
10. IC circuit unit